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Keeping the World Flowing  
for Future Generations

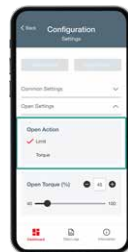
## IQ Range



Instructions for Safe Use, Installation,  
Basic Setup and Maintenance

**⚠ This manual contains important safety information. Please ensure it is thoroughly read and understood before installing, operating or maintaining the equipment.**

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## Table of Contents

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<b>1. Introduction</b>	<b>3</b>		
1.1 Identifying Actuator Parts	4		
1.2 Identifying IQ Actuator Type	5		
1.3 Setting Options	6		
1.4 Rotork App.	6		
1.5 Rotork Setting Tool	7		
<b>2. Health and Safety</b>	<b>8</b>		
2.1 ATEX, IECEx, UKEX and CSA Japan Certified Actuators.	10		
2.2 Indian Ex Certified Actuators	10		
<b>3. Storage</b>	<b>10</b>		
<b>4. Operating the IQ Actuator</b>	<b>11</b>		
4.1 IQ SET Actuators	11		
4.2 Operating by Hand.	11		
4.3 Operating Electrically	11		
4.4 Display – Local Indication	12		
4.5 Display – Home Screen Selection	13		
4.6 Display Status Indication – Travel	14		
4.7 Display Status Indication – Control.	14		
4.8 Display Alarm Indication.	14		
4.9 Battery Alarm.	14		
<b>5. Preparing the Drive Bush</b>	<b>15</b>		
5.1 IQ Base All Sizes Types A and Z3	15		
5.2 Non-Thrust Base Type B	16		
<b>6. Mounting the Actuator</b>	<b>17</b>		
6.1 Rising Stem Valves Top Mounted	18		
6.2 Valve with Gearbox – Side Mounting.	18		
6.3 Non-Rising Stem Valves – Top Mounting	18		
6.4 Handwheel Sealing.	19		
6.5 IQM Modulating Actuators	19		
6.6 IQL & IQML Linear Drive Unit	19		
6.7 IQL & IQML Adjusting Linear Stroke.	20		
6.8 IQL & IQML Lubrication	20		
<b>7. Cable Connections</b>	<b>21</b>		
7.1 Terminal Block Layout	21		
7.2 Earth/Ground Connections.	21		
7.3 Removing Terminal Cover.	21		
7.4 Cable Entry.	22		
7.5 Connecting to Terminals	22		
7.6 Replacing Terminal Cover.	23		
<b>8. Commissioning - Basic Settings</b>	<b>24</b>		
8.1 IQ SET Actuator Basic Settings.	25		
8.2 Connecting to the Actuator Using Rotork Setting Tool	27		
8.3 Connecting to the Actuator Using Manual Setup.	28		
8.4 Security – Password	29		
8.5 Basic Settings Menu	30		
8.6 Basic Settings – Limits	31		
8.7 Close Settings.	32		
8.8 Open Settings.	32		
8.9 Breakout Torque.	33		
<b>9. Maintenance, Monitoring and Troubleshooting</b>	<b>34</b>		
<b>10. Decommissioning and Environmental Considerations</b>	<b>36</b>		
<b>11. Weights and Measures</b>	<b>37</b>		
<b>12. IQ Approvals</b>	<b>39</b>		
<b>13. Approved Fuses</b>	<b>41</b>		
<b>14. Vibration, Shock and Noise</b>	<b>41</b>		
<b>15. Conditions of Safe Use</b>	<b>41</b>		
15.1 Thread details for ATEX, IECEx and UKEX approved actuators	41		
15.2 Maximum constructional flame path gaps for ATEX, IECEx and UKEX approved actuators.	42		

## 1. Introduction

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This manual provides instruction on:

- Manual and electrical (local and remote) operation
- Preparation and installation of the actuator onto the valve
- Basic commissioning
- Maintenance

**Refer to Publication PUB002-047 for repair, overhaul and spare part instructions.**

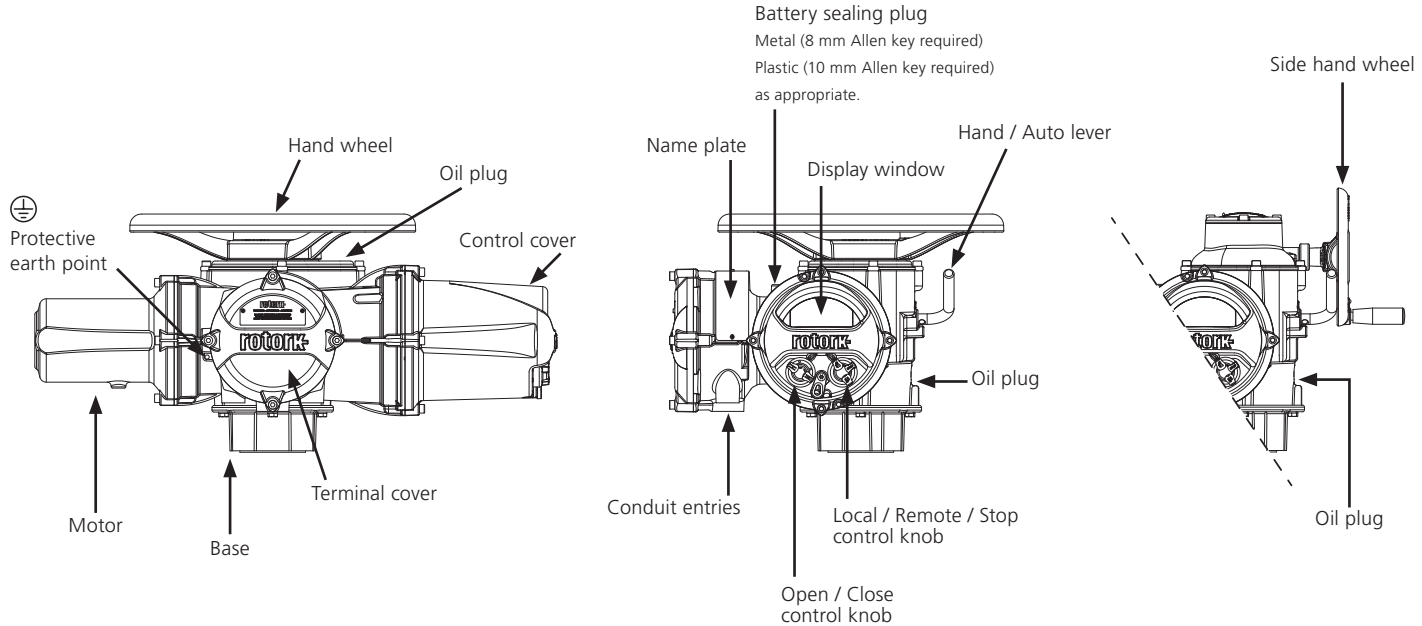
**Refer to Publication PUB002-040 for secondary function configuration instructions.**

Using one of the Setting Options identified in Section 1.3 to access the actuator set up procedures, non-intrusive setting of torque levels, position limits and all other control and indication functions can be made safely, quickly and conveniently, even in hazardous locations. The IQ allows commissioning and adjustment to be carried out with the main power supply to the actuator switched on or off.

Visit our website at [www.rotork.com](http://www.rotork.com) for more information on the IQ, Insight 2 and other Rotork actuator ranges.



## 1.1 Identifying Actuator Parts



## 1.2 Identifying IQ Actuator Type

### 1.2.1 IQ3 Actuator

Start-up screen shows IQ3 logo

Screen surround is black



### 1.2.2 IQ3 Pro Actuator

Start-up screen shows IQ3 Pro logo

Screen surround is red



OPEN/CLOSE control knob has positioning dots

### 1.3 Setting Options

There are three methods of configuring IQ3 actuators:

1. The Rotork app for smartphones (for IQ3 Pro only). See Section 1.4.
2. The Rotork Bluetooth® Setting Tool Pro (BTST) handset. See Section 1.5.
3. Manual setup using local control knobs on the actuator (for IQ3 Pro only). See Section 8.3.

### 1.4 Rotork App

The Rotork app provides a user-friendly interface that allows configuration of IQ3 Pro actuators from a smartphone running Android or iOS. For compatible versions with your device please check the app store.

For ease of setup, Rotork recommends that you use the Configuration Wizard in the app to configure actuators.

The Rotork app also provides a set of configuration screens and a Setting Tool functionality that mimics use of the BTST.

#### 1.4.1 Smartphone Connection via Bluetooth Wireless

As default from the factory, to connect a smartphone to the IQ3 Pro actuator, first make the actuator discoverable via Bluetooth wireless:

**⚠ Place the LOCAL/STOP/REMOTE control knob into STOP or REMOTE before proceeding.**

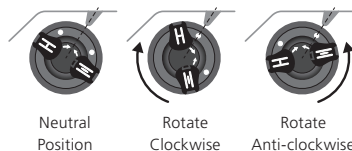


Fig. 1.4.1 OPEN/CLOSE local control knob

Move the OPEN/CLOSE control knob  $\frac{1}{8}$  turn clockwise **or** anti-clockwise, aligning one white dot with the notch on the casting. Hold it in this position for 2 seconds until the blue LED starts to flash, then release the knob.

The actuator will remain discoverable via Bluetooth wireless for approximately 2 minutes, during this time you can connect your smartphone following your phone's Bluetooth pairing instructions and start using the app.

If the actuator reverts to non-discoverable mode, repeat the instructions above.

#### 1.4.2 Rotork App Security

Communication between the smartphone and actuator is by Bluetooth wireless.

Access is granted using "PIN Pairing". When connection is made between the app and actuator, a PIN appears on the actuator screen which must be entered on the app to access the actuator configuration.

**⚠ The Rotork app and manual setup can also be enabled/disabled separately.**

**⚠ IQ3 actuators can be set to different levels of security. For explanations of the available security levels and instructions to implement them, see PUB002-040 IQ Range full configuration, status and monitoring user manual.**

## 1.5 Rotork Setting Tool

The Rotork Bluetooth® Setting Tool Pro v1.1 (BTST) combines the legacy IR and IrDA communication protocols with the latest Bluetooth wireless technology. IR / IrDA support for older Rotork products is retained for use as an IR communication tool. Refer to PUB002-003 and PUB002-004 for details.

The BTST is able to connect to Rotork Bluetooth wireless enabled actuators and related software to set up and complete missions. Missions are configurable sequences of instructions that are to be initiated and controlled by the BTST on an actuator and include (but are not limited to) downloading configuration and data logger files as well as uploading specific configurations to the actuator. Different missions can be programmed into the BTST via Insight 2.



Rotork Bluetooth® Setting Tool Pro v1.1

### Specification

Enclosure: IP54

The BTST has been built in accordance with the following standards:



II 1G  
Ex ia IIC T4 Ga  
CML 19ATEX2194  
IECEx CML 20.0054



CML 21UKEX2122



Ex ia  
Class 1, Div 1,  
Group A, B, C, D T4  
CSA19CA80005457



Ex ia IIC T4 Ga  
GB 3836.1-2021,  
GB 3836.4-2021  
GYJ20.1173X



Ex ia IIC T4 Ga  
CSAUK 20JPN025  
JNIOSH-TR-46-1(2015)  
JNIOSH-TR-46-6(2015)



Ambient Temperature Range:

T<sub>amb</sub> = -30 to +50 °C

Operating Range: Infrared 0.75m,  
Bluetooth 10m

Enclosure Materials: Polycarbonate  
resin containing 10% Carbon Fibre,  
Silicone Rubber

### Instructions for Safe Selection, Installation, Use, Maintenance and Repair

The following instructions relevant to safe use in a hazardous area apply to equipment covered by CSA certificate numbers 80005457, IECEx CML 20.0054, CML 19ATEX2194 and CML 21UKEX2122.

1. The BTST v1.1 may be used in Division 1, 2 and Zones 0, 1, 2 hazardous areas that require IIC, IIB or IIA protection and temperature class T1, T2, T3 or T4.

2. The following checks must be conducted on the BTST v1.1 prior to taking it into a hazardous area:

a. The BTST v1.1 function must be checked by ensuring a red or green LED illuminates on the front of the Setting Tool when any button is pressed. If an LED does not illuminate, the BTST v1.1 requires inspection and battery replacement.

b. The BTST v1.1 does not require assembly or dismantling, however suitable precautions must be taken if the BTST v1.1 may come into contact with damaging substances (e.g. solvents that degrade polymeric materials). Regular inspections must be performed to confirm enclosure damage is not apparent. Do not use the equipment if damage is present.

3. The BTST v1.1 is not intended to be repaired by the user. Repair of the equipment is only permitted by the manufacturer or an approved agent in accordance with applicable code of practice.

4. No user adjustment of the BTST v1.1 is required.

5. The BTST must be inspected every three months, in a safe (non-hazardous), dry area by suitably trained personnel, to ensure it has been maintained in accordance with the applicable code of practice.

6. Subject to the applicable code of practice, the batteries may be replaced in a non-hazardous area with one of the following types of Alkaline-Manganese or Zinc-Manganese 'AAA' size batteries:

- Duracell Procell type MN2400
- Energizer HighTech
- Duracell Ultra
- VARTA Industrial
- VARTA High Energy
- Panasonic Pro Power
- Eveready Super
- Duracell Chinese

7. The BTST v1.1 contains no other user-replaceable parts and it cannot be repaired by the user. If the BTST v1.1 is faulty or needs repairing, it must not be used.

**Refer to Publication PUB095-013 Rotork Actuator Setting Tool Pro v1.1 manual for full details and BTST user instructions.**

## 2. Health and Safety

This manual is produced to enable a competent user to install, operate, adjust and inspect Rotork IQ range valve actuators. Only persons competent by virtue of their training or experience should install, maintain and repair Rotork actuators.

In order to maintain the security of the actuator and any connected systems, it is recommended that operators / end users take appropriate measures to prevent access by unauthorised persons. This may include both measures to control or restrict physical access to the actuator, the selection of an appropriate security level within the actuator's settings and adopting a suitable actuator password prior to it being put into service. For instructions as to how to change the password and security level settings please refer to PUB002-040.

Under no circumstances should replacement parts be used in Rotork actuators, other than those supplied or specified by Rotork.

Work undertaken must be carried out in accordance with the instructions in this and any other relevant manuals.

If the actuator is used in a manner not specified in this manual and any other Rotork manual, the protection provided by the actuator may be impaired.

The user and those persons working on this equipment should be familiar with their responsibilities under any statutory provisions relating to the Health and Safety of their workplace. Due consideration of additional hazards should be taken when using the IQ range of actuators with other equipment. Should further information and guidance relating to the safe use of the Rotork IQ range of actuators be required, it will be provided on request.

The electrical installation, maintenance and use of these actuators should be carried out in accordance with the National Legislation and Statutory Provisions relating to the safe use of this equipment, applicable to the site of installation.

**For the USA:** NFPA70, National Electrical Code® is applicable.

**For Canada:** CEC, Canadian Electrical Code is applicable.

The mechanical installation should be carried out as outlined in this manual and also in accordance with relevant standards such as British Standard Codes of Practice. If the actuator has nameplates indicating that it is suitable for installation in hazardous areas then the actuator may be installed in Zone 1, Zone 21, Zone 2 and Zone 22 (Class I Division 1, Class II Division 1) classified hazardous area locations only. It should not be installed in hazardous area locations with an ignition temperature less than 135 °C, unless suitability for lower ignition temperatures has been indicated on the actuator nameplate.

It should only be installed in hazardous area locations compatible with the gas and dust groups stated on the nameplate.

The electrical installation, maintenance and the use of the actuator should be carried out in accordance with the code of practice relevant for that particular Hazardous Area certification.

No inspection or repair should be undertaken unless it conforms to the specific hazardous area certification requirements. Under no circumstances should any modification or alteration be carried out on the actuator, as this could invalidate the actuator's hazardous area approval certification.



Access to live electrical conductors is forbidden in the hazardous area unless this is done under a special permit to work, otherwise all power should be isolated and the actuator moved to a non-hazardous area for repair or attention.

**⚠ WARNING: Service Altitude**

Actuator installation is permitted up to 5,000 m with the following restrictions:

- Actuator power supply is not above 480 V
- Input and output connections must use the 24 VDC nominal supply
- Mains system must be TT, IT, TN-C-S and 3-phase / wire systems

Installation without restrictions must be less than 2,000 m as defined by IEC61010-1 (Safety requirements for electrical equipment for measurement, control and laboratory use).

**⚠ WARNING: Motor Temperature**

Under normal operation the temperature of the actuator's motor cover surfaces can exceed 60 °C above ambient.

**⚠ WARNING: Surface Temperature**

The installer/user must ensure that the actuator surface temperature rating is not influenced by external heating/cooling effect (e.g. valve/pipeline process temperatures).

**⚠ WARNING: Thermostat Bypass**

If the actuator is configured to bypass the motor thermostat then the hazardous area certification will be invalidated. Additional electrical hazards may occur when using this configuration. The user should ensure that any necessary additional safety measures are considered.

**⚠ WARNING: Enclosure Materials**

IQ Range of actuators are manufactured from aluminium alloy with stainless steel fasteners and the thrust bases are manufactured in cast iron.

The cover window is toughened glass which is retained with a 2-part silicone cement and the battery plug will be either stainless steel or PPS (Poly-Phenolyne Sulphide).

The user must ensure that the operating environment and any materials surrounding the actuator cannot lead to a reduction in the safe use of, or the protection afforded by, the actuator. Where appropriate, the user must ensure the actuator is suitably protected against its operating environment.

**⚠ WARNING: Operating by Hand**

With respect to handwheel operation of Rotork electric actuators, refer to Section 4.2.

**⚠ WARNING: Unit Weight**

The actuator weight is shown on the nameplate. Care must be taken to transport, move or lift the actuator safely. Lifting information is available in Section 6.

**⚠ WARNING: Unexpected Operation**

When powered on, actuators can operate unexpectedly. Users must make provision for electrical isolation to prevent unintended operation and associated hazardous events. The actuator's STOP control knob (when fitted) is not an isolator and must not be considered as an emergency stop.

**⚠ WARNING: Mobile Devices**

Where applicable, users must ensure that any windows, IOS or android mobile devices must be suitably certified in accordance with the requirements of the standards and codes adopted by the national jurisdiction. The device must at least maintain the same level of Ex protection as the actuator.

## 2.1 ATEX, IECEx, UKEX and CSA Japan Certified Actuators

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### Special Conditions

This actuator must only be located in areas where the risk of impact to the viewing window is low.

This equipment includes some exterior non-metallic parts including the protective coating. To avoid the possibility of static build up, cleaning must only be carried out with a damp cloth.

### **WARNING: External Enclosure Fasteners**

Enclosure fasteners are stainless steel grade A4-80 except for the following sizes and when marked on the nameplate as shown. In these cases the terminal cover fasteners are carbon steel grade 12.9. If in doubt check the grade marked on the relevant fastener or contact Rotork.

### Actuator Size: IQ/IQM/IQS 20 & 35 or IQ/IQM 25 or IQ 19

Ex d IIB T4 Gb (-30°C to +70°C)

Ex d IIB T4 Gb (-40°C to +70°C)

Ex d IIB T4 Gb (-50°C to +40°C)

Certificate No: CML 19ATEX1190X, CML 21UKEX1118 or IECEx CML 20.0050X

### Actuator Size: IQ/IQM 20 & 25 or IQS 20 or IQ 19

Explosionproof, Class I, Div 1, Groups B, C & D - CSAus approved

Model: IQ3FM - Explosionproof, Class I, Div 1, Groups B, C, D - FM approved

## 2.2 Indian Ex Certified Actuators

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### Special Conditions

The manufacturer has maintained more stringent flamepath gaps than required by the standard. User must refer to manufacturer before carrying out any repairs or refurbishment to the equipment. The gap specified in certificate drawings must never be exceeded.

The fastening screws for cover with spigot joint shall be stainless steel socket head cap screws of property class A4-80 and yield stress 240 MPa.

User should follow instructions given on the equipment nameplate for selection of cable and cable gland.

End user should follow manufacturer's instructions for replacement of the battery.

### **Bureau of Indian Standards (BIS)**

For details of BIS certification please visit [www.bis.gov.in](http://www.bis.gov.in)

## 3. Storage

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If the actuator cannot be installed immediately, store it in a dry place until it is ready for connection to incoming cables.

If the actuator has to be installed but cannot be cabled it is recommended that the plastic transit cable entry plugs are replaced with metal plugs which are sealed with PTFE tape.

The Rotork double-sealed construction will preserve internal electrical components perfectly if left undisturbed.

It is not necessary to remove any electrical compartment covers in order to commission the IQ actuator.

Rotork cannot accept responsibility for deterioration caused on-site once the covers are removed.

Every Rotork actuator has been fully tested before leaving the factory to give years of trouble-free operation, providing it is correctly commissioned, installed and sealed.

## 4. Operating the IQ Actuator

### 4.1 IQ SET Actuators

**⚠ IQ SET electrical operation is different to standard IQ.**

IQ SET actuators are identified by a label shown in Fig 4.1.1. Additionally, always check the nameplate for the following wiring diagram sequence:

xxxSxxxx where x = any number. The fourth character 'S' denotes an IQ SET.



Fig. 4.1.1 IQ SET Identification Label

**⚠ For IQ SET commissioning and operation procedures refer to Section 8.1. For IQ SET installation, follow procedures in Sections 5 through 7.**

### 4.2 Operating by Hand

**⚠ WARNING**

**With respect to handwheel operation of Rotork electric actuators, under no circumstances should any additional lever device such as a wheel-key or wrench be applied to the handwheel in order to develop more force when closing or opening the valve as this may cause damage to the valve and/or actuator or may cause the valve to become stuck in the seated/ backseated position.**

**Keep clear of the handwheel when engaging hand operation. Actuators driving valves via extension shafts may be subject to retained shaft torsion which can cause the handwheel to rotate when hand operation is engaged.**

⚠ To engage handwheel drive depress the Hand/Auto lever into "Hand" position and turn the handwheel to engage the clutch. The lever can now be released where it will return to its original position. The handwheel will remain engaged until the actuator is operated electrically when it will automatically disengage and return to motor drive.

If required for local lockout purposes the Hand/Auto lever can be locked in either position using a padlock with a 6.5 mm hasp.

Locking the lever in the "hand" position prevents electrical operation of the actuator moving the valve.

### 4.3 Operating Electrically

Check that power supply voltage agrees with that on the actuator nameplate. Switch on power supply. It is not necessary to check phase rotation.

**⚠ Do not operate the actuator electrically without first checking, using one of the Setting Options (see Section 1.3), that at least the Basic Settings have been made (refer to Section 8).**

#### Selecting Local/Stop/Remote Operation

The red control knob enables either Local or Remote control, lockable in each position using a padlock with a 6.5 mm hasp.

When the control knob is locked in the Local or Remote positions the Stop facility is still available. The control knob can also be locked in the Stop position to prevent electrical operation by Local or Remote control.



Fig. 4.3.1 IQ3 Pro Local Controls

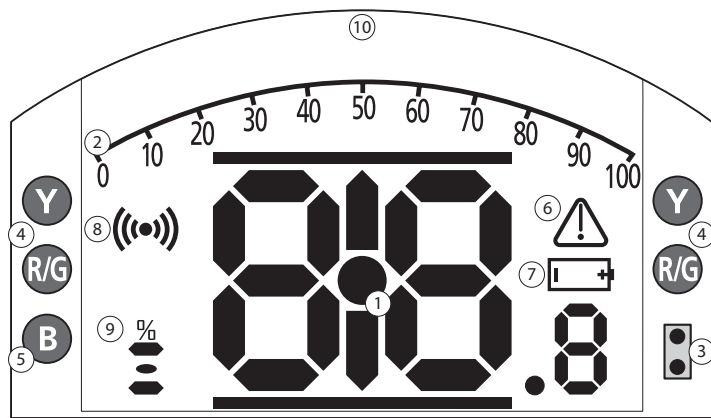
#### Local Control

With the red control knob positioned at Local (anti-clockwise) the adjacent black knob can be turned to select Open or Close. For Stop, turn red knob clockwise.

#### Remote Control

Rotate the red control knob to the Remote position (clockwise), this allows remote control signals to operate the actuator. Local Stop can still be used by turning the red knob anti-clockwise.

## 4.4 Display – Local Indication



**LED INDICATION: R = RED, G = GREEN, Y = YELLOW, B = BLUE**

Fig. 4.4.1 Segment Display

### 1. Position display

This is the main segment display for position and torque; position indication to 1 decimal place.

### 2. Analogue Scale

Scale 0% to 100% is used when Analogue torque (% of rated) or Positioning (% position / demand) homescreens are selected. Refer to Section 4.5.

### 3. Infrared LEDs

Used for older models of the Rotork Setting Tool and to initiate a data connection using Bluetooth wireless technology.

### 4. Dual position LEDs

Consisting of 2 x Yellow for mid position and 2 x bi-colour (Red / Green) for end of travel indication.

### 5. Bluetooth indication LED

A dual intensity LED for indicating an active connection using Bluetooth wireless technology.

### 6. Alarm Icon

This will be displayed for valve, control and actuator alarms. Alarm indication is supported by fault description in the text in the line above the main display.

### 7. Battery Alarm Icon

This icon will be displayed when a battery is detected as low or discharged. "Battery low" or "Discharged" will also be displayed in the text display above.

### 8. Infrared Icon

This icon flashes during Setting Tool communication activity. LEDs will also flash when keys are pressed.

### 9. Percentage Open Icon

This icon will be displayed when a percentage open value is displayed e.g. 57.3.

### 10. Dot Matrix Display

A high resolution 168x132 pixel display for displaying setup menus and data logger graphs.

When a positional display is active, the status and active alarms will be displayed.

The LCD screen is made up of two layers; the main segment display and the dot matrix display. The displays are dual stacked so that either display can be enabled to show different information. This also allows a combination of both displays for added flexibility.

On power the LCD is backlit with a white light to enable the best viewing contrast in all lighting conditions. For additional positional indication, the LEDs at either side of the LCD are used for Closed (green), mid-travel (yellow) and Open (red) as standard. These LEDs are fully configurable in the settings menu or on request at time of order.

## 4.5 Display – Home Screen Selection

The actuator display can be set to show any one of the following home screens:



- Position indication
- Position & Digital Torque indication
- Position & Analogue Torque indication
- Position & Control Demand indication

The default home screen is Position. Home screens indicate the live conditions measured by the actuator when mains power is applied. When mains power is switched off the actuator battery powers the display and it will show the position indication display only.

The required home screens can be set by the user either as a permanent display or as a temporary display for valve or actuator operational analysis.

**⚠ NOTE: Before using the displays, please ensure that the actuator is set to Local Control or Stop.**

### Temporary Home Screen display.

Using the Setting Tool (refer to Section 8.2)  or  arrow keys, scroll through the available home screens until the required one is displayed. The selected screen will remain displayed for approximately five minutes after the last Setting Tool command or until the actuator power is cycled. Manual setup can also be used to do this, as described in Section 8.3.

### Permanent Home Screen display.

Connect to the actuator using one of the Setting Options in Section 1.3.

From the **Settings** menu, select **Indication > Local Display**. From the available settings, select **Home Screen**. Enter the password if requested (refer to Section 8.4), select Home Screen and from the dropdown list, select the required Home Screen for permanent display:

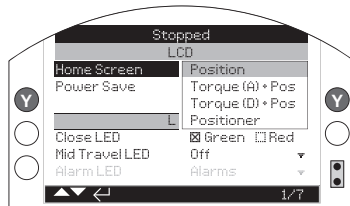


Fig. 4.5.1 Home Screen Selection

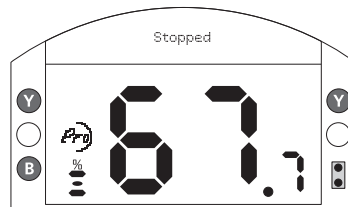


Fig. 4.5.2 Position

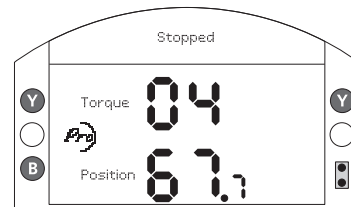


Fig. 4.5.4 Torque (D) + Position

### Position - Default valve position display

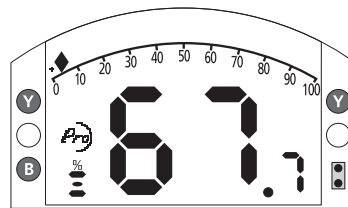


Fig. 4.5.3 Torque (A) + Position

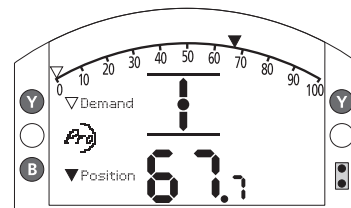


Fig. 4.5.5 Positioner

### Torque (A) + Pos - Position with analogue torque indication

### Positioner - Position with digital and analogue position demand indication

Once selected, the set display will be the active, permanent home screen.

#### 4.6 Display Status Indication – Travel

The IQ display provides real-time status indication. The top line of the text area is reserved for travel status indication.

Fig 4.6.1 shows the travel status example of **CLOSED LIMIT**

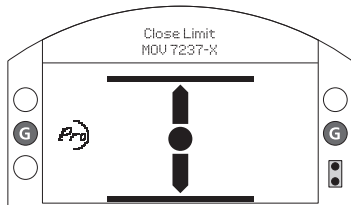


Fig. 4.6.1

#### 4.7 Display Status Indication – Control

The bottom line of the text area is reserved for control status indication and is displayed for approximately 2 seconds after the control mode or signal is applied.

Fig 4.7.1 shows the control status example **Remote Control**.

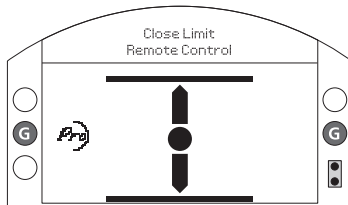


Fig. 4.7.1

#### 4.8 Display Alarm Indication

The IQ display provides alarm indication in the form of text and alarm icons.

There are 2 alarm icons:

General Alarm:



Battery Alarm:



The general alarm icon will be supported with text in the bottom line indicating the particular alarm, or if more than one is present, each alarm will be displayed in sequence.

Fig 4.8.1 shows the status example: **TORQUE TRIP CLOSED**

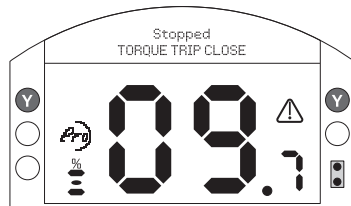


Fig. 4.8.1

#### 4.9 Battery Alarm

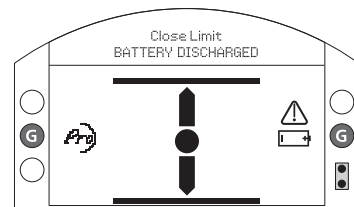


Fig. 4.9.1

The actuator checks the battery level at approximately 1 hour intervals. The battery alarm icon is displayed when the actuator detects its battery as being low and the display will indicate **BATTERY LOW**. If the battery is flat, or missing, the display will indicate **BATTERY DISCHARGED**.

When a low or discharged battery alarm is displayed the battery should be replaced immediately. It is essential that the correct battery type is fitted to maintain actuator certification. Refer to Section 9 for details.

**After replacing a battery the alarm icon will continue to be displayed until the next check and may take up to 1 hour. Cycling the power will force a battery check and clear the alarm.**

## 5. Preparing the Drive Bush

### 5.1 IQ Base All Sizes Types A and Z3

Turn actuator onto its side, remove the cap-headed screws holding retaining plate (1) onto the thrust base and pull out the drive bush (2) complete with its bearing assembly (3). Size IQ10 to 35 have 2 screws, size IQ40 to 95—F25 bases have 8 screws, and F30 have 10 screws. Before machining the drive bush the thrust bearing must be removed.

IQ10 to 18 actuators have a sealed thrust bearing located on the drive bush and retained by the split collar (4) and snap ring (5).

IQ20 to 95 have a thrust race bearing within a steel bearing housing located on the drive bush and retained by the split collar (4) and snap ring (5). The bearing is sealed within its housing by O-rings located on the drive bush and the bearing spacer ring (6).

**⚠ WARNING: Failure to remove the bearing assembly and O-rings from the drive bush prior to machining may result in damage to the bearing.**



Fig. 5.1.1

### Disassembly of bearing assembly all sizes

Locate and remove the snap ring (5) using a suitable tool. Remove the split collar (4) See Fig. 5.1.1. Slide the bearing (3) off the drive bush (2).

Note additional spacer (6) and O-rings to remove on sizes IQ20 to 95.

Keep the bearings and drive bush locating components in a safe clean place. The split collar (4) must be kept as a matched pair.

Machine the drive bush (2) to suit the valve stem, allowing a generous clearance on the screw thread for rising stem threads.



Fig. 5.1.2 F10 base assembly

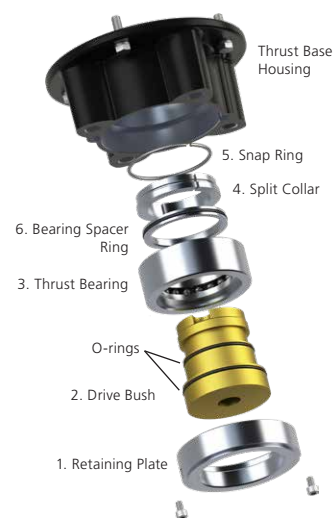


Fig. 5.1.3 F14 & F16 base assembly

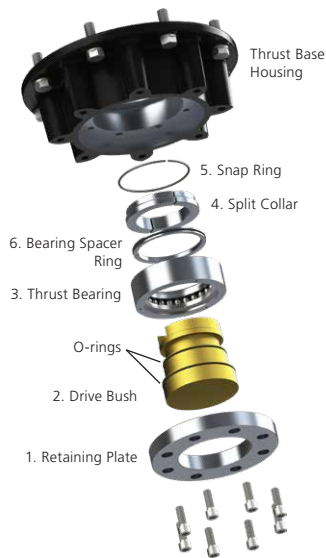


Fig. 5.1.4 F25 & F30 base assembly

## Reassembly

**⚠ WARNING: Failure to fully clean and grease the drive bush and O-rings before reassembly could result in damage.**

Remove all swarf from the drive bush (2) ensuring all O-rings are undamaged, clean and greased (for typical greases refer to Section 11, Weights and Measures).

Slide the bearing assembly (3) onto the drive bush (2) and ensure it is fitted down to the drive bush shoulder. On size IQ20 to IQ95 refit bearing spacer ring (6) into bearing assembly ensuring O-ring is fitted and greased. Grease and refit matched pair split collar (4) and snap ring (5).

Grease and refit the drive bush bearing assembly into the thrust base housing on the actuator, ensuring that the slots in the drive bush are located into the drive dogs of the hollow output shaft.

Refit the retaining plate (1) and secure with cap headed screws. For IQ40 to IQ95 tighten base retaining screws to the following torque values:

F25 / FA25 Base — 8 off / M12 cap head screws: 89 Nm / 65 lbs.ft

F30 / FA30 Base — 10 off / M16 cap head screws: 218 Nm / 160 lbs.ft

## 5.2 Non-Thrust Base Type B

### All Sizes

Undo the hex head bolts securing the base plate to the gearcase and remove the base plate.

The drive bush and its retaining clip can now be seen. The plate will vary with the size of the actuator. See Fig. 5.2.1.



Fig. 5.2.1



Fig. 5.2.2

### Types B3 and B4 Removal

Using external circlip pliers, expand the circlip while pulling on the drive bush. The drive bush will detach from the actuator centre column with the circlip retained in its groove. Refer to Fig. 5.2.2.

### Types B1 Removal

The procedure for removal and refitting of the B1 drive bush is the same as for B3 and B4, however the circlip is replaced with a custom spring circlip. The spring operates in the same manner as the B3/B4 circlip but is expanded using long nose-pliers. Refer to Fig. 5.2.3.

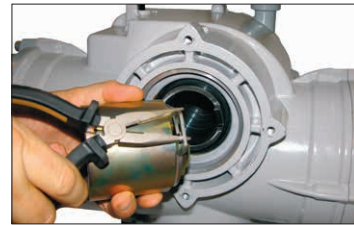


Fig. 5.2.3



## 6. Mounting the Actuator

### ⚠ Refer to Section 11 Weights and Measures for actuator weight.

Ensure the valve is secure before fitting the actuator as the combination may be top heavy and therefore unstable.

If it is necessary to lift the actuator using mechanical lifting equipment certified slings should be attached as indicated in Fig. 6.0.1 for vertical shafts and Fig. 6.0.2 for horizontal shafts.

At all times trained and experienced personnel should ensure safe lifting particularly when mounting actuators.

### ⚠ WARNING: The actuator should be fully supported until full valve shaft engagement is achieved and the actuator is secured onto the valve flange.

A suitable mounting flange conforming to ISO 5210 or USA Standard MSS SP101 must be fitted to the valve.

Actuator to valve fixing must confirm to material specification ISO Class 8.8, yield strength 628 N/mm<sup>2</sup>.

⚠ WARNING: IQ Cover Tubes. Cover tubes not supplied by Rotork shall be designed to ensure that they do not exceed BOTH mass and moment parameters listed in Section 11 Weights and Measures.

⚠ WARNING: Do not lift the actuator and the valve combination via the actuator. Always lift the valve/actuator assembly via the valve.

Each assembly must be assessed on an individual basis for lifting.



Fig. 6.0.1



Fig. 6.0.2

## 6.1 Rising Stem Valves Top Mounted

### Fitting the Actuator and Base as a combined unit, all sizes.

Fit the machined drive bush into the thrust base as previously described, lower the actuator onto the threaded valve stem, engage **HAND** operation and wind the hand wheel in the open direction to engage the drive bush onto the stem. Continue winding until the actuator is firmly down onto the valve flange. Wind two further turns, fit securing bolts and tighten fully to the required torque indicated in Table B.

### Fitting Thrust Base to Valve Actuator

Fit the machined drive bush into the thrust base as previously described. Remove the thrust base from the actuator, place it on the threaded valve stem with the slotted end of the drive bush uppermost and turn it in the open direction to engage the thread. Continue turning until the base is positioned onto the valve flange. Fit the securing bolts but do not tighten at this stage. Lower the actuator onto the thrust base and rotate the complete actuator until the drive dogs on the actuator output shaft engage into the drive bush. Actuator flange should now be flush with the base.

Continue to turn actuator until fixing holes align. Using bolts supplied fix actuator to thrust base and tighten down to required torque, see Table A.

Open valve by two turns and firmly tighten down onto valve flange to the required torque, see Table B.

It may not be possible to install the thrust base separately for IQ10 - IQ25 actuators with fireproof coating.



Fig. 6.1.1

Size	Torque ( $\pm 10\%$ )	
	Nm	lbs.ft
M8	13.8	9.8
M12	45.9	33.8
M16	101	74

Fig. 6.1.2 Table A

Metric		Torque	
Flange	Fixing	Nm	lbs.ft
F10	M10	51.6	38
F14	M16	219.8	162.1
F16	M20	430.5	317.5
F25	M16	219.8	162.1
F30	M20	430.5	317.5
Imperial		Torque	
Flange	Fixing	Nm	lbs.ft
FA10	$\frac{3}{8}$	42.3	31.2
FA14	$\frac{5}{8}$	205.3	151.4
FA16	$\frac{3}{4}$	363.6	268.1
FA25	$\frac{5}{8}$	205.3	151.4
FA30	$\frac{3}{4}$	363.6	268.1

Fig. 6.1.3 Table B

## 6.2 Valve with Gearbox – Side Mounting

Check that the mounting flange is at right angles to the input shaft, and that the drive bush fits the shaft and key with adequate axial engagement. Engage **HAND**, offer up actuator to the input shaft and turn handwheel to align keyway and key. Tighten mounting bolts to the required torque indicated in Table B.

## 6.3 Non-Rising Stem Valves – Top Mounting

Treat as for side mounting except that when thrust is taken in the actuator, a thrust nut must be fitted above the drive bush and securely tightened.

## 6.4 Handwheel Sealing

Ensure that the sealing cap and O-ring is fitted securely to ensure that moisture does not pass down the centre column of the actuator. For valves with rising spindles a cover tube may be fitted, this must also be sealed with an O-ring and secured with cap screws.



Fig. 6.4.1



Fig. 6.4.2

## 6.5 IQM Modulating Actuators

The IQM range of actuators are suitable for modulating control duty of up to 1,200 starts per hour.

IQM actuators have a dynamic braking facility as standard. If mechanical overrun of the actuator and valve prove to be excessive for accurate control, the brake can be enabled. With dynamic braking enabled, motor heating effects increase and therefore the number of starts may require reducing to prevent motor thermostat tripping.

Commissioning of the IQM range is identical to the standard IQ - refer to Section 8.

## 6.6 IQL & IQML Linear Drive Unit

Consists of a lead screw assembly arrangement attached to the base of the actuator in order to provide a linear output stroke between 8 mm ( $\frac{3}{4}$  in) minimum and 153 mm (6 in) maximum.

The IQL/IQML actuator can be supplied with or without a yoke mounting adaptor. The adaptor consists of four pillars and a base flange to suit the valve.

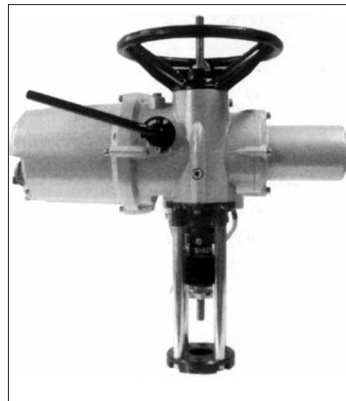


Fig. 6.6.1 IQML with Yoke

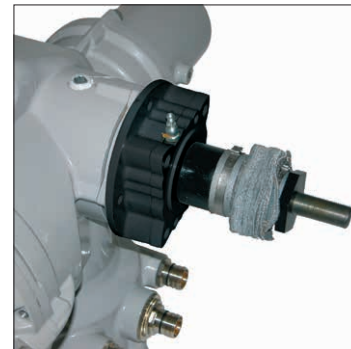


Fig. 6.6.2 IQML without Yoke

## 6.7 IQL & IQML Adjusting Linear Stroke

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With the actuator securely fitted to the valve, but with the linear drive disconnected, ensure valve is at its fully closed (down) position.

Turn the actuator handwheel clockwise, the linear drive will move down towards the valve spindle and couple the linear drive to the valve spindle.

Configure the actuator operating limits following instructions in Section 8.

## 6.8 IQL & IQML Lubrication

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The linear drive unit is lubricated from the factory with extreme pressure multi-purpose FUCHS RENOLIT CL X2 grease to suit all operating temperature ranges.

A grease nipple is situated in the base of the actuator to enable lubrication of the lead screw.

Apply two pumps of the specified grease from a standard grease gun every 30,000 starts. More frequent greasing may be necessary depending on usage and temperature.

## 7. Cable Connections

### 7.1 Terminal Block Layout

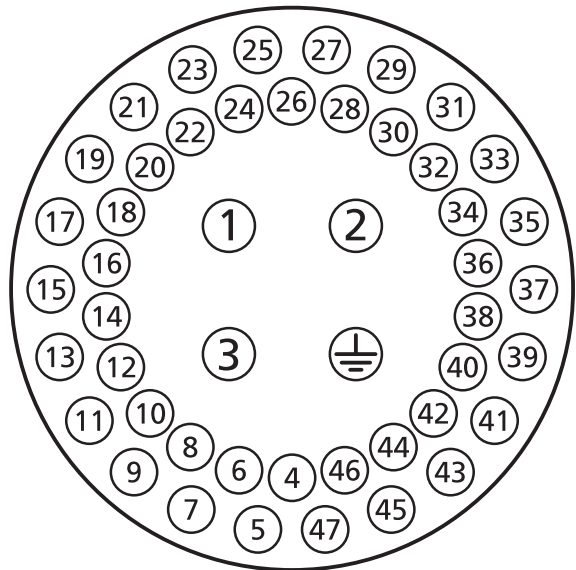


Fig. 7.1.1 Terminal numbers refer to connections as shown on the actuator circuit diagram

**⚠ WARNING: Ensure all power supplies are isolated before removing actuator covers.**

Check that the supply voltage agrees with that stamped on the actuator nameplate.

A switch or circuit breaker must be included in the wiring installation or the actuator. The switch or circuit breaker must meet the relevant requirements of IEC60947-1 and IEC60947-3 and be suitable for the application. The switch or circuit breaker must not disconnect the protective earth conductor. The switch or circuit breaker must be mounted as close to the actuator as possible and shall be marked to indicate that it is the disconnect device for that particular actuator. The actuator must be protected with overcurrent protection devices rated in accordance with the applicable electrical data publication:

- PUB002-099 (3-phase actuators)
- PUB002-019 (single-phase actuators)
- PUB002-120 (3-phase modulating actuators)
- PUB002-121 (DC actuators)

**⚠ WARNING: Actuators for use on phase to phase voltages greater than 600 V must not be used on supply systems where phase to earth voltages, pertinent to mains supply system type and nominal voltage, in excess of 600 VAC may exist; reference BS EN IEC 61010 - Annex I**

Power supply cables must have sufficient mechanical protection properties to meet installation requirements and be screened to comply with EMC requirements of the installed actuator. Suitable methods include armoured and/or screened cables or cables contained within conduit.

### 7.2 Earth/Ground Connections

A lug with a 6.5 mm diameter hole is cast adjacent to the conduit entries for attachment of an external protective earthing strap by nut and bolt. An internal earth connection is also provided however it must not be used alone as the Protective Earth Connection.

### 7.3 Removing Terminal Cover

Using a 6 mm Allen key loosen the four captive screws evenly. Do not attempt to lever off the cover with a screw driver this will damage the O-ring seal and may damage the flamepath on a certified unit.



Fig. 7.3.1

The Setting Tool is packed separately, with the actuator, in the shipping box identified with a yellow label.

The wiring code card fixed in the cover is particular to each actuator and must not be interchanged with any other actuator. If in doubt check the serial number on the code card with that of the actuator.



Fig. 7.3.2 Actuator terminal compartment (Setting Tool packed separately in shipping box).

A plastic bag in the terminal compartment contains:

- Terminal screws and washers
- Spare cover O-ring seal
- Wiring diagram
- Instruction book

## 7.4 Cable Entry

Only appropriate certified explosionproof cable glands or conduit may be used in hazardous locations. The cable entries in the actuator are tapped M25 x 1.5p or M40 x 1.5p.

In hazardous locations, only one appropriate certified explosionproof thread adaptor per entry may be used.

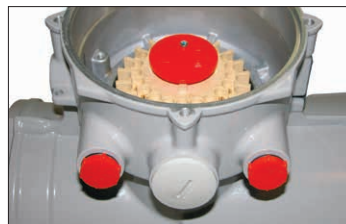


Fig. 7.4.1

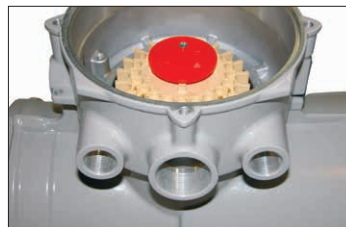


Fig. 7.4.2

Remove plastic transit plugs. Make cable entries appropriate to the cable type and size.

Ensure that threaded adaptors, cable glands or conduit are tight and fully waterproof. Seal unused cable entries with steel or brass threaded plug. In hazardous areas an appropriate certified threaded blanking plug must be installed at the cable entry without the use of an interposing thread adaptor.

## 7.5 Connecting to Terminals

Field wiring connections are by wire termination ring/spade tags. If necessary, suitable insulation must be applied to bare metal ring/spade tags in order to ensure adequate separation between 'hazardous live' and non-hazardous' live circuits considering, and in accordance with, national regulations and statutory provisions.

Tags are secured with the supplied 4 mm (control and indication) and 5 mm (power) pan head screws.

⚠ To ensure secure electrical connections, it is important that the requisite washers are used as shown in Fig. 7.5.1. Failure to do so may result in connections working loose or screws not clamping down on wire termination tags. Spring washers must be compressed. Screw tightening torques must not exceed 1.5 Nm (1.1 lbf.ft)

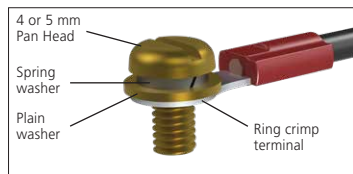


Fig. 7.5.1

⚠ To comply with Ex eb certification: Terminals numbered 1-3 & earth must be fitted with 1 off M5 insulated type ring tag suitable for 10 or 14 AWG conductors, Terminals numbered 4-47 must be fitted with 1 off M4 insulated type ring tag suitable for 14 or 16 AWG conductors. Only one conductor per ring tag is permitted.

Refer to the wiring diagram inside the terminal cover to identify functions of terminals. Check the supply voltage is the same as that marked on the actuator nameplate.

Remove power terminal guard.

Begin by connecting power cables and replace guard. When all connections are made ensure wiring diagram is replaced in the terminal compartment.

⚠ **WARNING: Wiring can reach 80 °C in a 70 °C ambient temperature. For safety reasons, the same voltage level must be connected to all the actuator's indication terminals, remote input terminals and digital I/O terminals (if applicable).**

All external circuits must be provided with insulation suitable for the rated voltage whilst considering national regulations and statutory provisions.

## 7.6 Replacing Terminal Cover

Ensure cover O-ring seal and spigot joint are in good condition and lightly greased before refitting cover. Please refer to Figure 7.3.1 when replacing the cover. Use a torque wrench and 6 mm Allen key to tighten the bolts evenly to a torque of 16 Nm (12 lbf.ft).



ATTENTION: RED PLASTIC PLUGS IN CONDUIT ENTRIES ARE FOR TRANSIT ONLY. FOR LONG TERM PROTECTION FIT SUITABLE METAL PLUGS.

ATTENZIONE: I TAPPI IN PLASTICA ROSSA PER L'ENTRATA CAVI SONO SOLO TEMPORANEI. PER UNA PROTEZIONE PERMANENTE PREGO SOSTITUIRLI CON APPOSITI TAPPI METALLICI.

ATENCION: LOS TAPONES ROJOS DE PLASTICO EN LAS ENTRADAS DE CABLE SON UNICAMENTE PARA TRANSPORTE. PARA PROTECCION PERMANENTE COLOCAR TAPONES METALICOS APROPIADOS.

ACHTUNG: DIE ROTEN PLASTIKSTOPFEN SIND NUR FÜR DEN TRANSPORT GEEIGNET. FÜR DAVERHAFTEN SCHUTZ SIND DIESE GEGEN GEEIGNETE BLINDSTOPFEN AUSZÜTAUSCHEN.

ATTENTION: LES BOUCHONS PLASTIQUES ASSURENT UNE PROTECTION TEMPORAIRE. POUR UNE PROTECTION DEFINITIVE UTILISER DES BOUCHONS METALLIQUES.

注意：コンジット口の赤色プラグは、輸送用を目的としたプラグです。長期に渡る保護の場合、適切なメタルプラグをご使用ください。

注意：接线端红色塑料封口仅为运输途中使用。长期正常保护时请用金属封口。

주의: 배선인입구의 빨간색 플라스틱 플러그는 오직 임시용입니다. 오래 보관하기 위해서는 규격에 맞는 금속 플러그를 사용하십시오.



## 8. Commissioning - Basic Settings

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All actuator settings, data logger and asset management data is accessed using one of the Setting Options listed in Section 1.3. Status and alarm data in addition to that shown on the home screen can also be accessed.

**THE CONTROL COVER MUST NOT BE REMOVED; NO USER-CONFIGURABLE SETTINGS ARE AVAILABLE WITHIN THE CONTROL ENCLOSURE. THE CONTROL COVER IS SEALED BY A QUALITY LABEL WHICH IF BROKEN MAY INVALIDATE WARRANTY.**

This instruction details the basic settings that must be completed before the actuator is put into service.

**ELECTRICAL OPERATION MUST NOT TAKE PLACE UNTIL THE BASIC SETTINGS HAVE BEEN MADE AND CHECKED.**

The basic settings affect the correct operation of the valve by the actuator. If the actuator has been supplied with the valve, the valvemaker or supplier may have already made these settings.

**⚠ Settings and operation must be verified by electric operation and function test of the actuated valve.**

**THIS PUBLICATION PROVIDES INSTRUCTION ON MAKING THE BASIC SETTINGS ONLY.**

For instruction on control and indication settings and for information on diagnostics refer to PUB002-040.



## 8.1 IQ SET Actuator Basic Settings

IQ SET actuators are designed to operate on the application of 3-phase power.

The applied phase rotation will determine the direction the actuator will move in.

This feature allows direct integration with the user's Motor Control Centre (MCC) comprising reversing contactors, HMI - DCS control elements (pushbuttons, PLC outputs etc.). Refer to the supplied actuator wiring diagram and referenced Rotork Wiring Schematic (RWS).

**Commissioning of IQ SET actuators may be undertaken under battery power or with power on and SET disabled. Refer to Section 8.2.**

**IQ SET actuators will power down when position limits and/or torque limits are reached. Move the handwheel a few degrees in the opposite direction to reinstate power and continue commissioning process.**

⚠ **IQ SET actuators must not be allowed to run the valve to end of travel until correct motor rotation and position limits have been established and verified.**

⚠ **The IQ SET open and closed torque/position limit contacts, shown on the wiring diagram, must be connected to the MCC open and close contactor coil circuits. On reaching a torque or position limit, the torque/position limit contact will open and de-energise the connected contactor.**

⚠ **Contactor coil circuit and indication circuits voltages are limited to 150 V maximum.**

⚠ **To prevent unexpected operation on power up, IQ SET actuators are dispatched with the IQ SET feature disabled. Once the limits have been set and verified, the IQ SET function may be enabled to allow operation from the user's MCC.**

### Checking IQ SET feature setting

⚠ **Ensure the 3-phase supply to the actuator is isolated.**

Using the handwheel, move the actuator and valve to a mid-travel position – the actuator display must indicate a numerical % open value (0% to 99% range). Wake the actuator up on battery power and using the Setting Tool connect to the actuator. Navigate to the **Settings** menu. Refer to Section 8.2.

From the **Settings** menu, select **Control > Local > SET**.

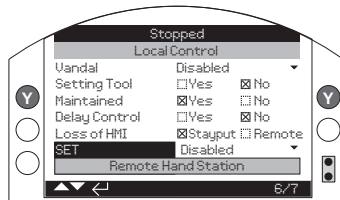


Fig. 8.1.1

Ensure the setting is **Disabled**. If not enter the password (Refer to Section 8.4) and use the keys to select **Disabled**.

Note the warning message when trying to change this setting:

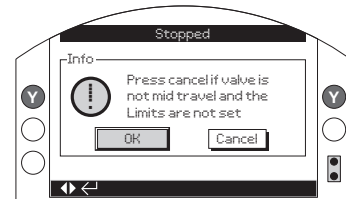


Fig. 8.1.2

The actuator will not power up if it is at the limit of the valve. Opposite contactor operation will allow power up, for instance if the actuator is at the Close Limit and the Open contactor is activated, the actuator will power up.

Press to confirm.

With the SET function disabled, apply the 3-phase power supply to the input terminals by activating either the open or close control for the MCC contactor.

The actuator will now power up without moving to allow limit settings to be made and verified.

Actuator alarm will be present on the screen when movement is inhibited in this mode (Fig 8.1.3). Refer to Section 4.8.

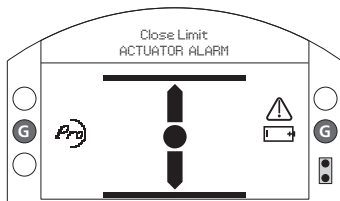


Fig. 8.1.3

### Setting IQ SET limit positions

Refer to Sections 8.5 through 8.7 for instructions. To set the close limit (4/15) and open limit (7/15), movement must be made using the handwheel.

**When setting the close limit position, ensure the MCC open contactor is energised. When setting the open limit position, ensure the MCC close contactor is energised.**

### Checking correct phase rotation

Once the limit positions, limit switch settings and remote wiring have been verified, move the actuator and valve to a mid-travel position by handwheel operation - the actuator display must indicate a numerical % open value (0% to 99% range) ideally between the ranges of 30% to 70% to allow the actuator to run for a few seconds without tripping power during verification of rotation.

**⚠ Ensure the 3-phase supply to the actuator is isolated.**

Wake the actuator up on battery power and using the Setting Tool connect to the actuator. Navigate to the Settings menu. Refer to Section 8.2. Enable the IQ SET feature:

From the **Settings** menu, select **Control > Local > SET**.

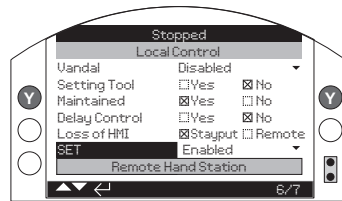


Fig. 8.1.4

Use the **⬇** **⬆** keys to change the setting to **Enabled**.

Press **⏹** to confirm.

Energise the MCC close contactor and confirm the actuator moves the valve in the close direction. If it moves “open”, de-energise the contactor immediately. Confirm isolation of the 3-phase power supply to the actuator. Swap any two phases connected to the actuator and retest.

**It is recommended that the direction of valve movement is confirmed by looking at the valve stem or gearbox indicator. For valves that require anti-clockwise (counter clockwise) actuator output movement to close, the Close direction setting must be set to “Anti” to make the IQ SET display indicate correctly. This setting will not change the actuator direction.**

## 8.2 Connecting to the Actuator Using Rotork Setting Tool

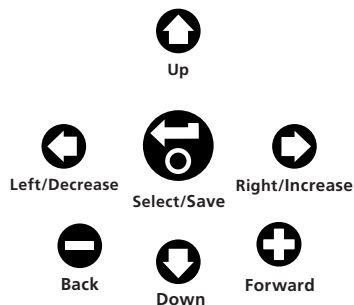
The Rotork Setting Tool incorporating Bluetooth wireless technology (Rotork Bluetooth® Setting Tool Pro v1.1 – BTST) is shown below. It is identified by the key symbols being clear and a clear seal between the top and bottom casings. The BTST has been produced with blue and black cases, with both having the same functionality.

The older infrared-only Rotork Setting Tool has a blue case with solid yellow keys and a yellow seal between casings.

Any of the above Setting Tools can be used with IQ3 or IQ3 Pro actuators.



Below are the relevant navigation and configuration keys to commission an IQ range actuator.



The actuator should be in LOCAL CONTROL or STOP before using the BTST.

Press the **Back** key repeatedly to return to the home screen.

### Connecting to the actuator using Bluetooth wireless

The default security set in the actuator for Bluetooth wireless connection is by initiation using an infrared command. This means that the user must be in close proximity and in direct line of sight of the actuator.

Point the Setting Tool at the actuator display window within a range 0.25 m (10 in) and Press **Down** key.

The screen will change to the Main Menu screen:

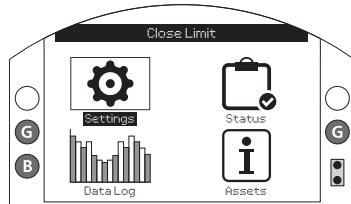


Fig. 8.2.1

**The Setting Tool will automatically connect using Bluetooth wireless which takes up to 5 seconds and when connected will be indicated by blue lights illuminating on the tool and in the actuator display window. Once connected, the tool can be used without pointing it at the actuator display window.**

Bluetooth wireless connection will be maintained while Setting Tool key commands are made. After a period of 6 minutes with no key commands, Bluetooth wireless connection will be turned off and the Setting Tool and display blue lights will go out. To manually turn off Bluetooth wireless connection at any time, press the Setting Tool **Back** and **Forward** keys together.

## 8.3 Connecting to the Actuator Using Manual Setup

This section describes how to use the manual setup feature introduced in Section 1.3.

### 8.3.1 Navigation and Commands

When using manual setup, the menus and commands displayed on the screen are navigated by using the OPEN/CLOSE control knob.

To navigate the screen, move the knob  $1/8$  turn clockwise or anti-clockwise, aligning one white dot with the notch on the casting. Hold the knob in this position for between 0.25 and 3 seconds.

To select a menu option, turn the knob fully ( $1/4$  of a turn) **clockwise**. Hold this position for 1 second. Release the knob to select the option.

To move backwards through a menu, turn the knob fully **anti-clockwise** ( $1/4$  of a turn) and hold for 1 second. On releasing the knob, the menu will go back one step.

To exit the Settings menu, repeatedly turn the knob anti-clockwise until you return to the home screen.

### 8.3.2 Manual Setup

**NOTE:** Manual setup is disabled by default. To enable this feature, follow the instructions below.

Place the LOCAL/STOP/REMOTE control knob into STOP or REMOTE before proceeding.

#### Step 1 – Activation

Using the BTST, navigate to **Settings > Indication > Local Display**

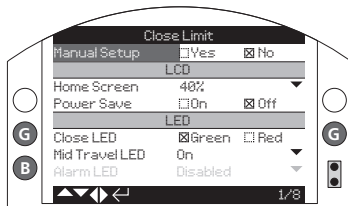


Fig. 8.3.3

Select **Manual Setup** and press the **OK** key.

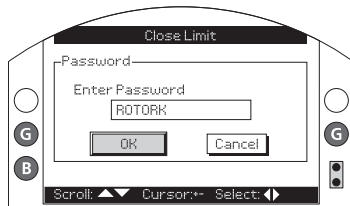


Fig. 8.3.4

Enter the actuator password and select **OK**.

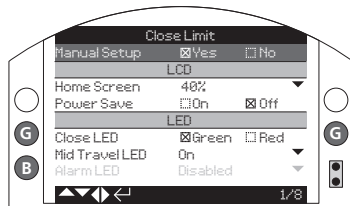


Fig. 8.3.5

Press the **Left** or **Right** key on the setting tool and select **Yes**. Press **OK** to confirm.

Once you have enabled the manual setup, initiation of app connection is no longer available through the method in Section 1.4.1. Please refer to Section 1.3 for other methods available for connection.

The Rotork app and manual setup can also be enabled/disabled separately.

#### Step 2 – Initiation

To initiate manual setup turn the OPEN/CLOSE control knob in the following sequence:

**clockwise > anti-clockwise > clockwise > anti-clockwise**

#### Step 3 – Exit Settings Menu

To exit the Settings menu:

1. Repeatedly turn control knob **anti-clockwise**, until the Home Screen is reached.
2. Set the LOCAL/REMOTE/STOP control knob to LOCAL.

Alternatively, the system automatically exits from manual setup if no commands are issued for 5 minutes.

## 8.4 Security – Password

**⚠ NOTE:** In this and subsequent sections the symbols shown correspond to the BTST keys. See Section 1 for the equivalent commands on the Rotork app and manual setup.

In order to maintain the security of the actuator and any connected systems, it is recommended that operators / end users take appropriate measures to prevent access by unauthorised persons. This may include both measures to control or restrict physical access to the actuator, the selection of an appropriate security level within the actuator's settings and adopting a suitable actuator password prior to it being put into service. For instructions as to how to change the password and security level settings please refer to PUB002-040.

The default security level for connecting to the actuator is by Bluetooth wireless initiation. Infrared connection requires that the user is at the actuator within 0.25 metre distance and in direct line of sight of the display. For instruction on connecting to the actuator refer to Section 8.2.

All actuator settings can be viewed with the actuator selected to LOCAL, STOP or REMOTE mode.

To change an actuator setting, the actuator must be selected to LOCAL or STOP or a correct password entered.

If the actuator is selected to REMOTE and a setting is selected, the following warning will be displayed:

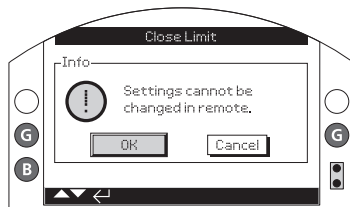


Fig. 8.4.1

Select **OK** to return to settings screen.

With the actuator selected to LOCAL or STOP and when any function is selected, the Password screen will be displayed:

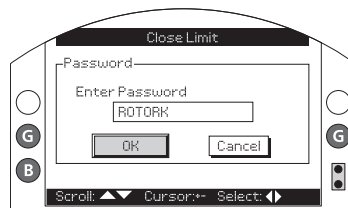


Fig. 8.4.2

The factory set default password ROTORK is displayed and the OK key is highlighted.

Press the **Ⓞ** key.

The setting screen will again be displayed. The example below shows **Settings > Limits > Close Settings** with the function **Action** highlighted:

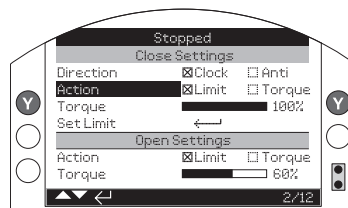


Fig. 8.4.3

Press the **Ⓞ** key to select.

The function and its setting option or range will then be highlighted:

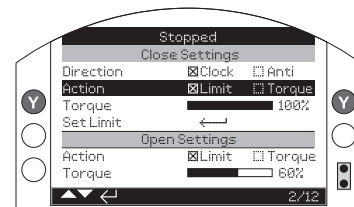


Fig. 8.4.4

If the user does not wish to change the function value, press the back button to escape without changing.

Use the ◀ or ▶ arrow keys to change the setting to the required value, the example below show a close action of **Torque** selected.

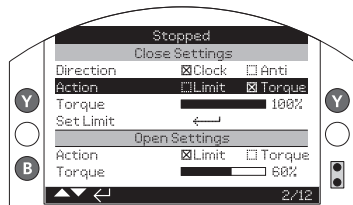


Fig. 8.4.5

Press the  key to save.

The highlight will return to the function name only and its stored setting will be displayed:

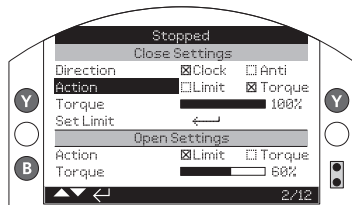
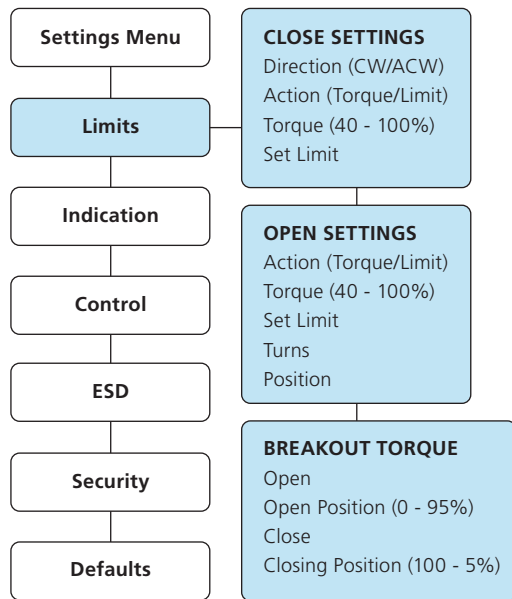


Fig. 8.4.6

The password will be requested the first time a function is selected. Once correctly entered, the password will not be required to be entered again for the duration of Setting Tool communication with the actuator. Other functions can be set as required.

## 8.5 Basic Settings Menu



## 8.6 Basic Settings – Limits

**⚠ Settings and operation must be verified by electric operation and function test of the actuated valve.**

Connect to the actuator as described in Section 8.2. From the Position display home screen press the **⏏** key. The main menu will be displayed.

Navigate to **Settings** using the **⏏** **⏏** keys and press **⏏** to select.

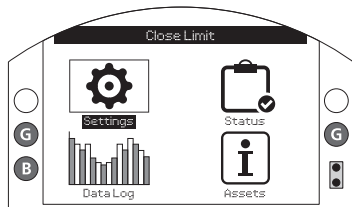


Fig. 8.6.1

The settings menu will be displayed:

Settings
Limits
Indication
Control
ESD
Security
Defaults

Navigate to **Limits** using the **⏏** **⏏** keys and press **⏏** to select.

**The setting first selected to be changed will require a password to be entered – refer to Section 8.4.**

The limit settings are shown below with their factory default values:





Limits	
Close Settings	
1 / 15	Direction <input checked="" type="checkbox"/> Clock <input type="checkbox"/> Anti
2 / 15	Action <input checked="" type="checkbox"/> Limit <input type="checkbox"/> Torque
3 / 15	Torque <input type="text" value="40%"/>
4 / 15	Set Limit <input type="text" value="←"/>
Open Settings	
5 / 15	Action <input checked="" type="checkbox"/> Limit <input type="checkbox"/> Torque
6 / 15	Torque <input type="text" value="40%"/>
7 / 15	Set Limit <input type="text" value="←"/>
8 / 15	Turns <input type="text" value="25"/>
9 / 15	Position <input type="text" value="95.0"/>
10 / 15	
Breakout Torque	
11 / 15	Opening <input type="checkbox"/> On X <input checked="" type="checkbox"/> Off
12 / 15	OP. Position <input type="text" value="10%"/>
13 / 15	Closing <input type="checkbox"/> On X <input checked="" type="checkbox"/> Off
14 / 15	CL. Position <input type="text" value="90%"/>
15 / 15	


Function Close Direction (1 / 15) is shown highlighted. Use **⏏** **⏏** to scroll through functions. Functions will be highlighted in turn. Blank settings are IQT only.


## 8.7 Close Settings

### 1 / 15. Close Direction

Function sets the direction required to close the valve. Manually operate the actuator and valve to establish closing direction.

Press  to select Close Direction function. Use  or  to check required setting. Press  to set.

 **For IQ SET actuators, the Close Direction setting will not affect the direction of movement. The direction of movement is dictated by the applied phase rotation only.**

 **For IQ SET actuators, Close Direction setting only changes the display indication. After verifying phase rotation, check display indication follows movement direction correctly. Refer to Section 8.1.**

### 2 / 15. Close Action

The actuator can be configured close on torque for seating valve types or limit for non-seating valve types.

 **Refer to valve manufacturer for recommended setting. In the absence of valvemaking instruction refer to the following table.**

Valve Type	Close Action	Open Action
Wedge gate	Torque	Limit
Globe	Torque	Limit
Butterfly*	Limit	Limit
Through conduit	Limit	Limit
Ball	Limit	Limit
Plug	Limit	Limit
Sluice gate	Limit	Limit
Penstock/Weir	Limit	Limit
Parallel slide	Limit	Limit
Diaphragm	Torque	Limit
Bellmouth	Limit	Limit
Knife gate	Limit	Limit

\* Butterfly valves are usually driven by part-turn actuators.

Press  to select Close Action function. Use  or  to check required setting. Press  to set.


### 3 / 15. Close Torque

The value of torque available to close the valve can be set between 40% and 100% of rated. The actuator rated torque value is shown on its nameplate.

Press  to select Close Torque function. Use  key to decrease value and  key to increase value.

Press  key to set.

### 4 / 15. Set Close Limit

Press  to select Close Limit Function. The actuator will display the following Instruction:

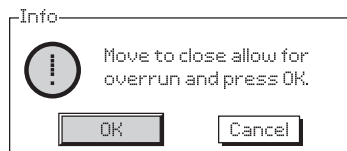



Fig. 8.7.1

Move the actuator and valve to the close position. Allow for overrun by winding in the opening direction by ½ to 1 turn.





Press  to set the close limit position.

## 8.8 Open Settings

### 5 / 15. Open Action

The actuator can be configured open on torque for seating valve types or limit for non-seating valve types.

 **Refer to Valve manufacturer for recommended setting. In the absence of valvemaking instruction set open action to "Limit".**

Press  to select Open Action function. Use  or  to check required setting. Press  to set.

### 6 / 15. Open Torque


The value of torque available to open the valve can be set between 40% and 100% of rated. The actuator rated torque value is shown on its nameplate.

Press  to select Open Torque function. Use  key to decrease value and  key to increase value.

Press  to set.



## 7 / 15. Set Open Limit

Press  to select Open Limit Function. The actuator will display the following instruction:

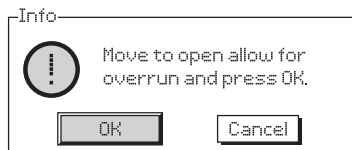



Fig. 8.8.1

Move the actuator and valve to the open position. Allow for overrun by winding in the closing direction by  $\frac{1}{2}$  to 1 turn.


Press  to set the open limit position.

## 8 / 15. Turns (not editable)

Shows the actuator output turns between the set Closed and Open limit positions.

## 9 / 15. Position (not editable)

Shows the actuator current position in terms of % open.

**Note: Turns and Position values do not update while being displayed on screen. To see updated values, use  key to return to Settings Menu, then select Limits.**


## 8.9 Breakout Torque

The default setting for opening and closing breakout torque is Off (torque protection active at all times). Bypassing the torque protection allows torque up to approximately 150% of rated to be available. The valvemaker/integrator should be consulted to confirm the valve structure and interface components can withstand the additional torque/thrust.

### 11 / 15. Opening

Opening torque protection can be bypassed over a configurable portion of the opening stroke. When enabled, torque up to approximately 150% of rated torque is available for opening “sticky” valves.

Press  to select Opening Breakout Torque function. Use  or  to check required setting.

Press  to set. You will be presented with a warning screen that informs you that setting opening breakout torque removes torque protection. You need to select OK or CANCEL.

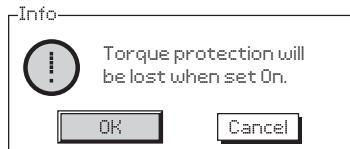






Fig. 8.9.1


### 12 / 15. OP position


When enabled (refer to 11 / 15), the position over the opening stroke where the torque protection is bypassed can be configured in the position range 0% (closed limit) to 95% open. Outside the bypass position, torque switch value will revert to that set, refer to 6 / 15.

Press  to select Opening Bypass Position function. Use  key to decrease value and  key to increase value. Press  to set.

### 13 / 15. Closing





Closing torque protection can be bypassed over a configurable portion of the closing stroke. When enabled, torque up to approximately 150% of rated torque is available for closing the valve. Outside the bypass position, torque switch value will revert to that set, refer to 3 / 15.

Press  to select Closing Breakout Torque function. Use  or  to check required setting.

Press  to set. You will be presented with a warning screen that informs you that setting closing breakout torque removes torque protection. You need to select OK or CANCEL.

### 14 / 15. CL position

When enabled (refer to 13 / 15), the position over the Closing stroke where the torque protection is bypassed can be configured in the position range 100% (open limit) to 5% open.

Press  to select Closing Bypass Position function. Use  key to decrease value and  key to increase value. Press  to set.

**Basic settings are now complete. For IQ SET start-up refer to Section 8.1 for instructions.**

## 9. Maintenance, Monitoring and Troubleshooting

### Maintenance

Every Rotork actuator has been fully tested before dispatch to give years of trouble-free operation providing it is installed, sealed and commissioned in accordance with the instructions given in this publication.

The IQ actuator's unique double-sealed, non-intrusive enclosure provides complete protection for the actuator components.

The IQ actuator gearing is located in an oil bath and is lubricated for life and does not need replenishing. Should the oil be removed or lost, the actuator must not be electrically operated, as premature failure may result.

Covers should not be removed for routine inspection as this may be detrimental to the future reliability of the actuator.

The electrical control module cover is bonded by the Rotork quality control seal. It should not be removed as the module contains no site-serviceable components.

All electrical power supplies to the actuator must be isolated before any maintenance or inspection is carried out, except replacement of the battery.

Electrical supplies must be isolated before actuator covers are removed – refer to battery replacement instructions.

Routine maintenance should include the following:

- Check actuator to valve fixing bolts for tightness
- Ensure valve stems and drive nuts are clean and properly lubricated
- If the motorised valve is rarely operated, a routine operating schedule should be set up
- Replace actuator battery every 5 years
- Check the actuator enclosure for damage, loose or missing fasteners
- Ensure there is not an excessive build up of dust or contaminant on the actuator
- Check for any loss of lubricant. (refer to Section 11 for lubricants)

### The Actuator Battery

The battery supports the actuator valve position indication relays, data logger and the position display (LCD) only when the main power supply is turned off. It ensures the current position is indicated and displayed when manual operation takes place.

The battery is not required to retain any actuator settings or track position changes.

With mains power switched off and without a battery fitted or when discharged, all configured settings are retained safely in EEPROM and position changes are tracked by the absolute encoder.

On power up, the correct, current position will be displayed and the actuator will operate normally.

**⚠ WARNING: The battery holder in the actuator gearcase also protects the user from the hazardous live connections inside the actuator and therefore it must not be damaged. The actuator must be isolated or disconnected if the battery holder has to be removed from the actuator gearcase.**

A unique circuit has been incorporated into the battery function of the IQ, effectively reducing the overall drain and significantly increasing the battery life.

**In normal circumstances battery replacement interval should not exceed 5 years. Ambient temperature and plant operating conditions may affect battery life.**

Battery level status is indicated by an icon on the actuator display – refer to Section 4.4.

If the battery icon is displayed the battery should be replaced to ensure correct power off valve position indication.

**⚠ WARNING:**

### Battery Replacement

**If the actuator is located within a hazardous area permission must be obtained in the form of a "hot work permit" or other local regulation before removal and/or replacement of the battery.**

Removal of the battery with the main electrical power switched off will result in stored data logger records time reference being lost for the duration when there is no mains and battery power. It is therefore recommended that the battery is replaced with the main electrical supply to the actuator switched on.

### Battery Removal

The actuator must be selected to Stop using the red control knob – refer to Section 4.3. Access to the battery is via a labelled sealing plug situated on the main gearcase near the handwheel hub.

Remove the sealing plug using the appropriate Allen key, ensuring the O-ring seal remains on the plug. Disconnect the battery wiring loom from the battery terminals. Using the black pull strap, lift the battery out of the rubber sealing pocket.



Fig. 9.0.1

### Battery Types

For International, EU and UK hazardous area certified actuators, use a lithium manganese dioxide battery as stated in Fig. 9.0.2 Battery Type Table.

For USA and Canada hazardous area certified actuators, use an Ultralife U9VL lithium manganese dioxide battery. Equivalent, UL recognised, batteries may be used.

For non-hazardous actuators, Rotork recommend a lithium manganese dioxide battery, however any equivalent 9V battery may be used.

If in doubt regarding the correct battery type, contact Rotork.

Enclosure Type	Battery Type	Detail
Standard Temp	Ultralife PP3 Types	U9VL or U9VL-J-P
Low/High Temp	Rotork Part Numbers:	95-462 or 95-614

Fig. 9.0.2 Battery Type Table

### Fitting Replacement Battery

Fit the pull strap around the replacement battery and insert into the rubber sealing pocket. Reconnect the battery wiring loom to the battery terminals. Refit the battery sealing plug ensuring O-ring is in good condition and correctly fitted. Hand tighten the sealing plug to 8 Nm (6 lbs/ft) using the appropriate Allen key.

### Oil

Unless specially ordered for extreme climatic conditions, Rotork actuators are dispatched with gearcases filled with SAE 80EP oil which is suitable for ambient temperatures ranging from -30 to +70 °C (-22 to +160 °F).

IQ actuators do not require regular oil changes (refer to Section 11, Weights and Measures).

### Torque and Position Monitoring

The IQ range of actuators incorporate real time, instantaneous Torque & Position monitoring as standard. Torque & Position can be used to monitor valve performance during operation. The effect of process changes (differential pressure etc.) can be evaluated, tight spots in valve travel can be pinpointed as well as gauging the torque developed through stroke in order to set appropriate open and closed torque switch settings.

There are two home screen displays that indicate torque and position simultaneously. Refer to Section 4.5.

### Analogue Torque and Position indication

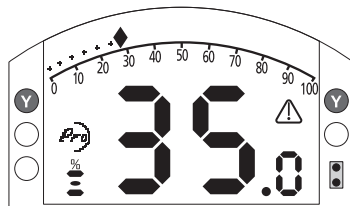


Fig. 9.0.3

Example shows that actuator at 35.0% open, producing 27% of rated torque. The warning triangle indicates the actuator has torque tripped.

Note: The torque and position values displayed are dynamic and will show the actual torque and position values currently measured. After a torque trip, the torque value tends to drop away as the internal mechanical components relax as no drive is present.

### Digital Torque and Position indication

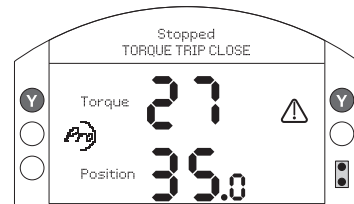


Fig. 9.0.4

Example shows that actuator at 35.0% open, producing 27% of rated torque. The status bar and warning triangle indicate that the actuator has torque tripped when closing.

Note: The actuator will torque trip and stop when the value of torque reaches that set for the open (when opening) and closing (when closing) torque switches (refer to Sections 8.6 and 8.7). Due to the effects of inertia (variable with speed/load) and valve resilience, the torque delivered and displayed may be higher.

## 10. Decommissioning and Environmental Considerations

End user advice on disposal at end of life of the product.

In all cases check local authority regulation before disposal.

The actuator can be removed by reversing the operations detailed in the mounting and cabling sections.

All warnings as detailed in the mounting and cable connection sections must be followed. Disposal of the actuator or any of its components should be done in accordance with the table below.

**⚠ WARNING: It is essential that the actuator is not subject to any valve / system loads at the time of removal as this could cause operator injury due to the actuator moving unexpectedly.**

Subject	Definition	Remarks / examples	Hazardous	Recyclable	EU Waste Code	Disposal
Batteries	Lithium	IQ battery	Yes	Yes	16 06 06	Will require special treatment before disposal, use specialist recyclers or waste disposal companies
	Alkaline	Setting Tool	Yes	Yes	16 06 04	
Electrical & Electronic Equipment	Printed circuit boards	All products	Yes	Yes	20 01 35	Use specialist recyclers
	Wire	All products	Yes	Yes	17 04 10	
Glass	Lens/Window	IQ	No	Yes	16 01 20	Use specialist recyclers
Metals	Aluminium	Gearcases and covers	No	Yes	17 04 02	Use licensed recyclers
	Copper/Brass	Wire, IQ gears, motor windings	No	Yes	17 04 01	
	Zinc	IQ clutch ring and associated components	No	Yes	17 04 04	
	Iron/Steel	Gears and bases	No	Yes	17 04 05	
	Mixed Metals	IQ motor rotors	No	Yes	17 04 07	
Plastics	Glass filled nylon	Covers, electronics chassis	No	No	17 02 04	Disposal as general commercial waste
	Unfilled	Gears	No	Yes	17 02 03	Use specialist recyclers
Oil /Grease	Mineral & Kerosene Mixed	Gearbox lubrication	Yes	Yes	13 07 03	Will require special treatment before disposal, use specialist recyclers or waste disposal companies
	Mineral	Gearbox lubrication	Yes	Yes	13 02 04	
	Food Grade	Gearbox lubrication	Yes	Yes	13 02 08	
	Grease	Side handwheel / linear drive	Yes	No	13 02 08	
Rubber	Seals & O-rings	Cover and shaft sealing	Yes	No	16 01 99	May require special treatment before disposal, use specialist waste disposal companies

## 11. Weights and Measures

### Lubricating oil

Refer to actuator name plate. IQ actuators are lubricated using the oil grades specified below. They are factory-filled for life and in normal service do not require topping up.

Ambient temperature ranges:

**Standard** -30 to 70 °C (-22 to 158 °F):  
FUCHS TITAN GEAR MPSAE80 APIGL-4 lubricating oil.†

**Low Temp** -50 to 40 °C (-58 to 104 °F):  
Mobil SHC 624 lubricating oil.†

**M61** -61 to 40 °C (-78 to 104 °F):  
FUCHS RENOLIN ZAF15LT lubricating oil.†

### Food grade lubricating oil

If user-specified, IQ actuators will be filled with HYDRA LUBE GB† food grade lubricating oil suitable for temperature range -20 to 70 °C (-4 to 160 °F).

### Grease – Side handwheels

FUCHS CASSIDA GREASE CLEAR 2 FOOD or equivalent for all temperature ranges.

### Grease – Linear drive unit

IQL and IQML linear drive assemblies should be regularly lubricated using FUCHS RENOLIT CL X2. See Section 6.8.

### Grease – Base assembly

O-rings use FUCHS CASSIDA GREASE CLEAR 2 FOOD or equivalent for all temperature ranges.

Oil capacity is shown on the actuator oil capacity label. Only use the oil capacities stated in this manual if an oil fill label is not present.

### Standard weight and lubricating oil capacities:

Actuator Size	Weight kg (lbs)	Oil Capacity litres (pt.-US)
IQ10	31 (68)	1.25 (2.64)
IQ12	31 (68)	1.25 (2.64)
IQ18	31 (68)	1.25 (2.64)
IQ19	54 (119)	1.9 (4.0)*
IQ20	54 (119)	1.9 (4.0)*
IQ25	54 (119)	1.9 (4.0)*
IQ35	75 (165)	2.4 (5.1)
IQ40	145 (320)	3.7 (7.8)
IQ70	145 (320)	3.7 (7.8)
IQ90	160 (353)	3.7 (7.8)
IQ91	150 (331)	3.7 (7.8)
IQ95	160 (353)	3.7 (7.8)

### Inverted installation

If inverted installation (base uppermost) was specified with the order, Rotork will oil fill to the quantities shown in the table below and the actuator will be labelled "Factory filled with additional oil for inverted use". If not specified with order but site installation will be inverted, to ensure adequate lubrication the installer must top up the oil before installation using the top oil plug by the amount indicated in the table.

For oil plug location, refer to Section 1.1.

### Inverted installation lubricating oil capacities:

Actuator Size	Inverted Oil Capacity litres (pt.-US)	Top-up quantity litres (pt.-US)
IQ10, 12, 18	1.25 (2.64)	0.0 (0.0)
IQ19, 20, 25	1.90 (4.0)*	0.0 (0.0)
IQ35	2.75 (5.81)	0.35 (0.74)
IQ40, 70, 90, 91, 95	5.7 (12.04)	2.0 (4.23)

† Oils and lubricants are subject to change due to supply availability at our worldwide manufacturing facilities. For detailed information please contact your local Rotork agent.

\* Oil capacity shown for Top Hand Wheel actuators. Side Hand Wheel actuator capacity is 2.20 l (4.65 pt.-US).

## IQ Cover tubes

Cover tubes not supplied by Rotork shall be designed to ensure that they do not exceed BOTH mass and moment parameters listed in the table below.

They shall also be of a suitable material for the application and be suitably finished and protected for the environmental conditions.

If cover tubes exceed these parameters (due to weight, length, wind, etc.) they must be properly supported.

Frame size	Maximum mass (kg)	Maximum mass (lbs)	Maximum moment* (Nm)	Maximum moment* (lbf.ft)
IQ10 – IQ18	5	11	305	225
IQ19 – IQ25	11	24.3	690	509
IQ35	17	37.5	955	704
IQ40 – IQ95	17	37.5	955	704

\*Moment measured about centre of cover tube bolt mounting PCD.

## 12. IQ Approvals

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Refer to actuator nameplate for unit specific approval details.

### International – Hazardous Area

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IECEx. IEC 60079-0, IEC 60079-1,  
IEC 60079-7, IEC 60079-31  
& ISO 80079-36

Ex db<sup>1</sup> h IIB T4 Gb IP66/IP68

Ex h tb IIIC T120°C Db

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

Ex db<sup>1</sup> h IIC T4 Gb IP66/IP68

Ex h tb IIIC T120°C Db

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

<sup>1</sup> Ex eb added if the terminal enclosure  
is increased safety.

### EU & UK – Hazardous Area

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ATEX (2014/34/EU)

UKEX (2016 No. 1107)

II 2 G D

Ex db<sup>1</sup> h IIB T4 Gb IP66/IP68

Ex h tb IIIC T120°C Db

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

Ex db<sup>1</sup> h IIC T4 Gb IP66/IP68

Ex h tb IIIC T120°C Db

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

<sup>1</sup> Ex eb added if the terminal enclosure  
is increased safety.

### USA – Hazardous Area

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FM & CSAus - Explosionproof and  
Dust Ignition Proof to NEC Article 500,  
FM 3600, FM 3615 and FM 3616.

Class I, Division 1, Groups C & D

Class II, Division 1, Groups E, F & G

Temperature -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

Class I, Division 1, Groups B, C & D

Class II, Division 1, Groups E, F & G

Temperature -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

## **Brazil – Hazardous Area**

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**INMETRO certification**

**Ex db IIB T4 Gb**

**Ex tb IIIC T120°C Db, IP66 & IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +70°C (-58°F to +158°F)

**Ex db IIC T4 Gb**

**Ex tb IIIC T120°C Db, IP66 & IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +70°C (-58°F to +158°F)

**Ex db eb IIB T4 Gb**

**Ex tb IIIC T120°C Db, IP66 & IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +70°C (-58°F to +158°F)

**Ex db eb IIC T4 Gb**

**Ex tb IIIC T120°C Db, IP66 & IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +70°C (-58°F to +158°F)

## **Canada – Hazardous Area**

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**CSA Explosionproof to C22.2 No. 30**

**CSA Dust Ignition Proof to C22.2**

**No. 25**

**Class I, Division 1, Groups C & D**

**Class II, Division 1, Groups E, F & G**

Temperature -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

**Class I, Division 1, Groups B, C & D**

**Class II, Division 1, Groups E, F & G**

Temperature -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

## **China – Hazardous Area (CCC Ex)**

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**2020322307001142 &**

**2020322307001124**

**GB 3836.1 – 2021, GB 3836.2 – 2021**

**GB 3836.3 – 2021, GB 3836.31 – 2021**

**Ex db IIB T4 Gb**

**Ex tb IIIC T120°C Db IP66/IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

**Ex db IIC T4 Gb**

**Ex tb IIIC T120°C Db IP66/IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

**Ex db eb IIB T4 Gb**

**Ex tb IIIC T120°C Db IP66/IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

**Ex db eb IIC T4 Gb**

**Ex tb IIIC T120°C Db IP66/IP68**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

## **China – Hazardous Area (CCC Ex)**

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**2020322307000647 &**

**2020322307000648**

**GB 3836.1 – 2021, GB 3836.2 – 2021**

**GB 3836.31 – 2021**

**Ex db IIB T4 Gb**

**Ex tb IIIC T120°C Db**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

**Ex db IIC T4 Gb**

**Ex tb IIIC T120°C Db**

Temperature -20°C to +70°C (-4°F to +158°F)

\*Option -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)



## India – Hazardous Area

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IS/IEC-60079-0, IS/IEC-60079-1

Ex db IIB T4 Gb

Temperature -20°C to +70°C (-4°F to +158°F)

Ex db IIC T4 Gb

Temperature -20°C to +70°C (-4°F to +158°F)

## Japan – National Standard –

### Explosion Proof Area

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National Standard Explosionproof

JNIOSH-TR-46-1(2015)

JNIOSH-TR-46-2(2015)

Ex d IIB T4 Gb

IP66 & IP68

Temperature -20°C to +60°C (-4°F to +140°F)

Certificate Number: CSAUK 20JPN008X

Ex d IIC T4 Gb

IP66 & IP68

Temperature -20°C to +60°C (-4°F to +140°F)

Certificate Number: CSAUK 21JPN012X

労 (令和2.1) 検	労 (令和3.9) 検
CSAUK 20JPN008X	CSAUK 21JPN012X
ROTORK CONTROLS LTD	ROTORK CONTROLS LTD

## International – Non-Hazardous

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Ingress Protection BS EN60529

IP66 & IP68, (7 metres for 72 hours).

Temperature -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

## USA – Non-Hazardous

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Enclosure Type 4 & 6

Temperature -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

## Canada – Non-Hazardous

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Enclosure Type 4, 4X & 6

Temperature -30°C to +70°C (-22°F to +158°F)

\*Option -40°C to +70°C (-40°F to +158°F)

\*Option -50°C to +40°C (-58°F to +104°F)

Rotork can supply actuators to national standards not listed above. For details please contact Rotork.

### 13. Approved Fuses

FS1 = Bussman TDC11 (rating as per transformer type. See actuator wiring diagram for transformer type).

Type 1 = 250 mA anti-surge

Type 2 = 250 mA anti-surge

Type 3 = 150 mA anti-surge

FS2 (ATEX, IECEx and UKEX units only)

Bussman TDS 500 - 100 mA Quickblow  
or Littell Fuse 217 - 100 mA Quickblow

### 14. Vibration, Shock and Noise

Standard IQ range actuators are suitable for applications where vibration and shock severity does not exceed the following:

Type	Level
Plant induced vibration	1g rms total for all vibration within the frequency range of 10 to 1000 Hz
Shock	5g peak acceleration
Seismic	2g acceleration over a frequency range of 1 to 50 Hz if it is to operate during and after the event
Emitted noise	Independent tests have shown that at 1m generated noise does not exceed 65 db(A)

### 15. Conditions of Safe Use

#### EMC

The equipment is intended for use in an industrial electromagnetic environment.

#### 15.1 Thread details for ATEX, IECEx and UKEX approved actuators

Threaded Flamepath	Thread Size	Thread Length	Actuator Type and Size
Battery Cover	M40x1.5	10.00	All Types and Sizes
Cable Entry	M25x1.5	20.00	All Types and Sizes
	M40x1.5	20.00	All Types and Sizes

## 15.2 Maximum constructional flamepath gaps for ATEX, IECEx and UKEX approved actuators

Flamepath	Max. Gap (mm)	Min. Length (mm)	Actuator Type and Size
Motor Cover / Gearcase	0.15	25.00	IQ10, IQ12, IQ18, IQ19, IQ20, IQ25, IQ35, IQM10, IQM12, IQM20, IQM25, IQS12, IQS20, IQS35, IQ40, IQ70, IQ90, IQ91, IQ95
Wormshaft Shroud / Gearcase	0.05	35.00	IQ10, IQ12, IQ18, IQM10, IQM12, IQS12
		38.00	IQ19, IQ20, IQ25, IQM20, IQM25, IQS20
		35.00	IQ35, IQS35
Wormshaft Shroud / Gearcase	-0.04/0.00	49.75	IQ40, IQ70, IQ90, IQ91, IQ95
Wormshaft / Wormshaft Shroud	0.24	26.00	IQ10, IQ12, IQ18, IQM10, IQM12, IQS12
		26.00	IQ19, IQ20, IQ25, IQM20, IQM25, IQS20
		27.00	IQ35, IQS35
Wormshaft / Wormshaft Shroud	0.25	49.75	IQ40, IQ70, IQ90, IQ91, IQ95
Terminal Bung Gearcase (IIB)	0.20	27.00	All Types and Sizes
Terminal Bung Gearcase (IIC)	0.115	27.00	All Types and Sizes
Terminal Cover / Gearcase	0.15	27.00	All Types and Sizes
Electrical Cover / Gearcase	0.15	26.00	All Types and Sizes
Encoder Shaft / Encoder Shaft Bush	0.08	27.00	All Types and Sizes
Encoder Shaft Bush / Gearcase	0.07	25.00	All Types and Sizes
Motor Loom Bush / Gearcase	0.15	28.75	IQ10, IQ12, IQ18, IQ19, IQ20, IQ25, IQ35, IQM10, IQM12, IQM20, IQM25, IQS12, IQS20, IQS35
		33.25	IQ40, IQ70, IQ90, IQ91, IQ95
DC Motor Adaptor / Gearcase	0.15	25.00	IQD10, IQD12, IQD18, IQD20, IQD25
DC Motor Cover / DC Motor Cover Adaptor	0.15	12.50	IQD10, IQD12, IQD18, IQD20, IQD25

**Note:** Negative sign denotes an interference fit.

# rotork®



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**[www.rotork.com](http://www.rotork.com)**

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